## Exercises in Optimization (ACM 40990 / ACM41030)

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Exercises #2

## Exercises #2 - More on Line-search Methods

1. In the notes (Chapter 6), it is shown that the Newton method satisfies:

$$\|m{x}_{k+1} - m{x}_{*}\|_{2} \leq C \|m{x}_{k} - m{x}_{*}\|_{2}^{2}$$
 whenever  $\|m{x}_{k} - m{x}_{*}\|_{2} < \delta$ .

If we choose

$$\|oldsymbol{x}_0-oldsymbol{x}_*\|_2<\delta, ext{ and } \|oldsymbol{x}_0-oldsymbol{x}_*\|<rac{1}{2C}$$

then

$$\frac{\|\boldsymbol{x}_1 - \boldsymbol{x}_*\|_2}{\|\boldsymbol{x}_0 - \boldsymbol{x}_*\|_2} \le C \|\boldsymbol{x}_0 - \boldsymbol{x}_*\|_2 \le \frac{1}{2}.$$

The aim of this exercise is to show that these inequalities give rise to the following important result:

$$\frac{\|\boldsymbol{x}_k - \boldsymbol{x}_*\|_2}{\|\boldsymbol{x}_0 - \boldsymbol{x}_*\|_2} \le \frac{1}{2^{2^k - 1}}.$$

The proof of the inequality (1) can be obtained by the following sequence of steps:

(a) Write down inequalities for

$$egin{aligned} \|m{x}_1 - m{x}_*\|_2 &\leq rac{1}{2^{\cdots}} \|m{x}_0 - m{x}_*\|_2, \qquad \|m{x}_2 - m{x}_*\|_2 &\leq rac{1}{2^{\cdots}} \|m{x}_0 - m{x}_*\|_2, \ \|m{x}_3 - m{x}_*\|_2 &\leq rac{1}{2^{\cdots}} \|m{x}_0 - m{x}_*\|_2. \end{aligned}$$

(b) Hence, guess that the general term satisfies

$$\|m{x}_k - m{x}_*\| \le rac{1}{2^{p_k}} \|m{x}_0 - m{x}_*\|_2,$$

where

$$p_k = 2p_{k-1} + 1. (2)$$

(c) Equation (2) is a first-order **difference equation** with general solution  $p_k = A + B\lambda^n$ , where A, B, and  $\lambda$  are constants to be determined. Hence, show that  $p_k$  satisfies:

$$p_k = 2^k - 1, \qquad k > 1$$

with  $p_1 = 1$ .

(d) Conclude that

$$\|m{x}_k - m{x}_*\|_2 \le rac{1}{2^{2^k-1}} \|m{x}_0 - m{x}_*\|_2,$$

and hence,

$$\lim_{k\to\infty} \|\boldsymbol{x}_k - \boldsymbol{x}_*\|_2 = 0.$$

2. Show that if  $0 < c_2 < c_1 < 1$ , there may be no step lengths that satisfy the Strong Wolfe conditions.

Hint: Consider the quadratic function

$$\phi(\alpha) = a + b\alpha + c\alpha^2,$$

where b < 0 and c > 0.

3. Consider the one-dimensional function

$$\phi(\alpha) = f(\boldsymbol{x}_k + \alpha \boldsymbol{p}_k),$$

where  $p_k$  is a descent direction – that is,  $\phi'(0) < 0$  – so that our search can be confined to positive values of  $\alpha$ . Find the value that minimizes  $\phi(\alpha)$  in the case where the cost function is quadratic, specifically:

$$f(\boldsymbol{x}) = \langle \boldsymbol{a}, \boldsymbol{x} \rangle + \frac{1}{2} \langle \boldsymbol{x}, B \boldsymbol{x} \rangle, \tag{3}$$

where  $\boldsymbol{a} \in \mathbb{R}^n$  and  $B \in \mathbb{R}^{n \times n}$ .

- 4. Consider the steepest decent method with exact line searches applied to the convex quadratic function in Equation (3).
  - (a) Show that if the initial point is such that  $x_0 x_*$  is parallel to an eigenvector of B, then the steepest descent method will find the solution in one step.
  - (b) Show that the Newton method always converges in exactly one step when the cost function is quadratic, i.e. takes the form (3).
- 5. Consider the optimization problem,

min 
$$f(\boldsymbol{x})$$
,  $f(\boldsymbol{x}) = \langle \boldsymbol{a}, \boldsymbol{x} \rangle + \frac{1}{2} \langle \boldsymbol{x}, B \boldsymbol{x} \rangle$ ,

where now B is a specific  $10 \times 10$  matrix and a is a specific  $10 \times 1$  column vector. The numerical values of these arrays can be found in the spreadsheet OP\_10x10.csv:

- The spreadsheet contains a  $10 \times 1$  array which corresponds to the vector  $\boldsymbol{a}$ ;
- The spreadsheet contains a  $10 \times 10$  array  $B_0$ .

The array B is obtained from  $B_0$  by the following sequence of steps:

(i) Symmetrize  $B_0$ :

$$B_0 \to (B_0 + B_0^T)/2;$$

(ii) Scale  $B_0$ :

$$B_0 \to B_0 / \max(|B_0|)$$

(iii) Generate a positive-definite matrix:

$$B_0 \to (B_0^T) B_0.$$

The end result of this sequence of operations is the matrix B. Hence,

- (a) Find the minimizer  $x_*$  numerically, using the steepest-descent and Newton algorithms.
- (b) Why is the convergence so poor in the case of the steepest-descent algorithm?