Braced sphere triangulations and rigidity

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IWOTA Lancaster

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Outline

Introduction to rigidity

Survey of recent work in normed spaces

A new result for doubly braced triangulations

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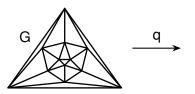
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X finite dimensional real normed linear space.

$$G = (V, E)$$
 simple undirected graph.

$$q \in X^V$$
, $q = (q_v)_{v \in V}$.

The pair (G,q) is called a bar-joint framework in X.





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Standard question: Is (G,q) rigid or flexible in X?

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Typical theorem: Graphs of type A are rigid in spaces of type B for all placements of type C.

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Image: A matrix

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Typical theorem: Graphs of type A are rigid in spaces of type B for all placements of type C.

Target theorem: A graph is rigid in a given space for almost all placements iff it satisfies the following purely combinatorial (and easily verifiable) conditions...

$$\lim_{t \to 0} \frac{1}{t} \left(\|q_v + tu_v - (q_w + tu_w)\| - \|q_v - q_w\| \right) = 0.$$

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$$\lim_{t \to 0} \frac{1}{t} \left(\|q_v + tu_v - (q_w + tu_w)\| - \|q_v - q_w\| \right) = 0.$$

 $\mathcal{F}(G,q)$ is the linear space of infinitesimal flexes of (G,q).

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An infinitesimal flex $u \in \mathcal{F}(G,q)$ is trivial if there exists η in the Lie algebra of Isom(X) such that

$$u_v = \eta(q_v), \quad \forall v \in V.$$

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 $\mathcal{T}(G,q)$ is the linear space of trivial infinitesimal flexes of (G,q).

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(G,q) is minimally rigid if it is rigid and $(G \setminus e,q)$ is flexible for every edge $e \in E$.

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G is (minimally) rigid in *X* if there exists $q \in X^V$ such that (G, q) is (minimally) rigid in *X*.

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G is (minimally) rigid in *X* if there exists $q \in X^V$ such that (G, q) is (minimally) rigid in *X*.

Theorem (Folklore)

G is minimally rigid in \mathbb{R} iff it is a tree.

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Survey of recent work in normed spaces

A new result for doubly braced triangulations

G = (V, E) is (k, l)-sparse if $|E'| \le k|V'| - l$ for "all" subgraphs (V', E').

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G is (k, l)-tight if it is (k, l)-sparse and |E| = k|V| - l.

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G is (k, l)-tight if it is (k, l)-sparse and |E| = k|V| - l.

Theorem (Maxwell 1864) If *G* is minimally rigid in ℓ_2^d then *G* is $\left(d, \frac{d(d+1)}{2}\right)$ -tight.

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Theorem (Geiringer 1927, Laman 1970) *G* is minimally rigid in ℓ_2^2 iff it is (2,3)-tight.

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Theorem (Geiringer 1927, Laman 1970) *G* is minimally rigid in ℓ_2^2 iff it is (2,3)-tight.

Longstanding open problem: Find a combinatorial characterisation of rigidity in ℓ_2^d , where $d \ge 3$.

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Theorem (Gluck 1975, Whiteley 1990)

Triangulations of the 2-sphere are minimally rigid in ℓ_2^3 .

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Theorem (Gluck 1975, Whiteley 1990)

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Theorem (Fogelsanger 1988)

Triangulations of compact surfaces without boundary are rigid in ℓ_2^3 .

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Image: A matrix

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Triangulations of the 2-sphere are minimally rigid in ℓ_2^3 .

Theorem (Fogelsanger 1988)

Triangulations of compact surfaces without boundary are rigid in ℓ_2^3 .

Theorem (Cruickshank, K., Power 2019)

Triangulations of a torus with a single hole are minimally rigid in ℓ_2^3 iff they are (3, 6)-tight.

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A new result for doubly braced triangulations



Workshop on Geometric Rigidity, Lancaster 2015

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The rigidity matrix R(G,q) takes the form,

where $\varphi(v, w)$ is the (unique) support functional for $q_v - q_w \in X$.

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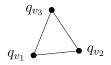
$$\blacktriangleright \mathcal{F}(G,q) = \ker R(G,q).$$

•
$$\mathcal{T}(G,q)$$
 depends on $\mathrm{Isom}(X)$.

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A new result for doubly braced triangulations

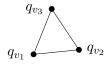
Example Let $X = \ell_2^2$ and $G = K_3$. Write $q_v = (q_v^x, q_v^y)$ for all $v \in V$.



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Example Let $X = \ell_2^2$ and $G = K_3$. Write $q_v = (q_v^x, q_v^y)$ for all $v \in V$. R(G, q) is a $|E| \times 2|V|$ -matrix:



$$\begin{array}{c} & \begin{pmatrix} (v_1;x) & (v_1;y) & (v_2;x) & (v_2;y) & (v_3;x) & (v_3;y) \\ \\ v_1v_2 \\ v_1v_3 \\ v_2v_3 \end{pmatrix} \begin{pmatrix} q_{v_1}^x - q_{v_2}^x & q_{v_1}^y - q_{v_2}^y & q_{v_2}^x - q_{v_1}^x & q_{v_2}^y - q_{v_1}^y & 0 & 0 \\ \\ q_{v_1}^x - q_{v_3}^x & q_{v_1}^y - q_{v_3}^y & 0 & 0 & q_{v_3}^x - q_{v_1}^x & q_{v_3}^y - q_{v_1}^y \\ \\ 0 & 0 & q_{v_2}^x - q_{v_3}^x & q_{v_2}^y - q_{v_3}^y & q_{v_3}^x - q_{v_2}^x & q_{v_3}^y - q_{v_2}^y \end{pmatrix}$$

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Theorem (K., Power 2014)

Let $p \in [1, \infty]$, $p \neq 2$. Then G is minimally rigid in ℓ_p^2 iff it is (2, 2)-tight.



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Theorem (K., Power 2014) Let $p \in [1, \infty]$, $p \neq 2$. Then *G* is minimally rigid in ℓ_p^2 iff it is (2, 2)-tight.

Conjecture Let $p \in [1, \infty]$, $p \neq 2$. Then *G* is minimally rigid in ℓ_p^d iff it is (d, d)-tight.

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Conjecture Let $p \in [1, \infty]$, $p \neq 2$. Then *G* is minimally rigid in ℓ_p^d iff it is (d, d)-tight.

Theorem (Dewar, K., Nixon 2021)

Triangulations of the projective plane are minimally rigid in ℓ_p^3 , for all $p \in (1, \infty)$, $p \neq 2$.

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Theorem (K. 2015)

Let X be a normed plane with a polygonal unit ball. Then G is minimally rigid in X iff it is (2,2)-tight.

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Theorem (K. 2015)

Let X be a normed plane with a polygonal unit ball. Then G is minimally rigid in X iff it is (2,2)-tight.

Theorem (Dewar 2019)

Let X be a non-Euclidean normed plane. Then G is minimally rigid in X iff it is (2,2)-tight.

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Theorem (K., Levene 2020)

Let $p \in [1, \infty]$, $p \neq 2$.

(i) If G is minimally rigid in $(\mathcal{M}_n(\mathbb{R}), \|\cdot\|_{c_p})$ then it is $(n^2, 2n^2 - n)$ -tight.

(ii) If G is minimally rigid in $(\mathcal{H}_n(\mathbb{R}), \|\cdot\|_{c_p})$ then it is $(\frac{1}{2}n(n+1), n^2)$ -tight.

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A new result for doubly braced triangulations



Geometric constraint systems, Lancaster 2019

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Joint work with James Cruickshank (NUI Galway), Eleftherios Kastis (Lancaster) and Bernd Schulze (Lancaster).

See our recent preprint:

Cruickshank, Kastis, Kitson, Schulze. Braced triangulations and rigidity. arxiv.org/abs/2107.03829

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An edge e of P is contractible in G if it is contractible in P and does not belong to any 3-cycle that contains a brace.

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Image: A matrix

An edge e of P is contractible in G if it is contractible in P and does not belong to any 3-cycle that contains a brace.

A braced sphere triangulation is irreducible if it has no contractible edges.

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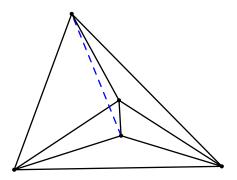
A braced sphere triangulation is irreducible if it has no contractible edges.

Theorem

An irreducible braced sphere triangulation with b braces has at most 11b - 4 vertices.

Theorem

There is exactly one irreducible unibraced sphere triangulation.



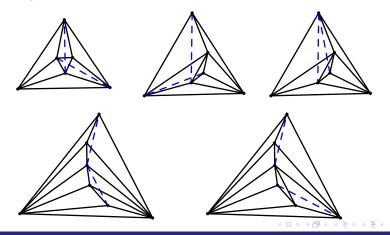
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Theorem

There are exactly five irreducible doubly braced sphere triangulations.



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For $p \in (1,\infty)$ define the mixed norm on \mathbb{R}^3 by,

$$||(x, y, z)||_{2,p} = ((x^2 + y^2)^{\frac{p}{2}} + |z|^p)^{\frac{1}{p}}.$$

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Theorem Doubly braced triangulations are minimally rigid in $(\mathbb{R}^3, \|\cdot\|_{2,p})$, for all $p \in (1, \infty)$, $p \neq 2$.

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Conjecture Doubly braced triangulations are minimally rigid in $(\mathcal{H}_2(\mathbb{R}), \|\cdot\|_{c_p})$, for all $p \in [1, \infty]$, $p \neq 2$.

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Proof.

Every doubly braced sphere triangulation can be constructed from one of 5 irreducibles by "vertex splitting".

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Image: A matrix

Proof.

Every doubly braced sphere triangulation can be constructed from one of 5 irreducibles by "vertex splitting".

The 5 irreducibles are minimally rigid in $(\mathbb{R}^3, \|\cdot\|_{2,p})$.

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Image: A matrix

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Proof.

Every doubly braced sphere triangulation can be constructed from one of 5 irreducibles by "vertex splitting".

The 5 irreducibles are minimally rigid in $(\mathbb{R}^3, \|\cdot\|_{2,p})$.

Vertex splitting preserves minimal rigidity in smooth and strictly convex normed spaces.

Thank you, Steve!

Congratulations and enjoy your retirement!

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