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- The diffusion equation,

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\frac{\partial u}{\partial t}=\sigma \frac{\partial^{2} u}{\partial x^{2}}
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## The Finite Difference Method

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Suppose we choose to approximate this PDE with the FDE

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\frac{U_{j}^{n+1}-U_{j}^{n}}{\Delta t}+c \frac{U_{j}^{n}-U_{j-1}^{n}}{\Delta x}=0
$$

Space-Time Grid:
Space axis horizontal
Time axis vertical


To repeat:

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- [2] For a given time $t>0$, will the solution of the FDE converge to that of the PDE as $\Delta x \rightarrow 0$ and $\Delta t \rightarrow 0$ ?

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Warning: Sometimes superscript $n$ denotes a power; sometimes it is just an index. Be careful!

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The FDE is consistent with the PDE if, in the limit $\Delta x \rightarrow 0$ and $\Delta t \rightarrow 0$, the FDE coincides with the PDE.

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If the difference (local truncation error) goes to zero as $\Delta x \rightarrow 0, \Delta t \rightarrow 0$, then the FDE is consistent with the PDE.

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\left(u_{t}+\frac{1}{2} u_{t t} \Delta t+\cdots\right)_{j}^{n}+c\left(u_{x}-\frac{1}{2} u_{x x} \Delta x+\cdots\right)_{j}^{n} \simeq 0
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Subtracting the PDE gives the local truncation error:

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\tau=\left(\frac{u_{t t}}{2}\right) \Delta t-\left(\frac{c u_{x x}}{2}\right) \Delta x+\text { H.O.T. }=O(\Delta t)+O(\Delta x)
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Truncation errors are a crucial factor in determining forecast accuracy in NWP.

## Convergence and Stability

The second question posed above was whether the solution of the FDE converges to the PDE solution.

That is, if we let $\Delta x \rightarrow 0$ and $\Delta t \rightarrow 0$, so that $j \Delta x \rightarrow x$ and $n \Delta t \rightarrow t$, does $U(j \Delta x, n \Delta t) \rightarrow u(x, t)$ ?

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which has the solution $u(x, t)=u(x-c t, 0)$.
The shape of the solution $u(x, 0)$ translates along the $x$-axis with velocity $c$ (see Figure below).


Schematic of the solution of the advection equation (for $c>0$ ).

The FDE for the upstream scheme can be written as

$$
U_{j}^{n+1}=(1-\mu) U_{j}^{n}+\mu U_{j-1}^{n}
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where

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\mu \equiv \frac{c \Delta t}{\Delta x}
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Then the FDE solution at the new time level $U_{j}^{n+1}$ is interpolated between the values $U_{j}^{n}$ and $U_{j-1}^{n}$.
In this case the advection scheme works the way it should, because the true solution lies in between those values.


Schematic of the relationship between $\Delta x, \Delta t$ and $c$ leading to interpolation of the solution at time-level $n+1$.

$$
0<\mu \equiv \frac{c \Delta t}{\Delta x}<1
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However, suppose this condition is not satisfied, so that

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Then the parcel arriving at point $x_{j}$ at time $t_{n+1}$ comes from somewhere outside the interval $\left(x_{j-1}, x_{j}\right)$ at time $t_{n}$.
[Recall that $\partial u / \partial t+c \partial u / \partial x=0$ is a linear approximation to $d u / d t=0$.]

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[Recall that $\partial u / \partial t+c \partial u / \partial x=0$ is a linear approximation to $d u / d t=0$.]
Thus, the value of $\mathrm{U}_{j}^{n+1}$ is extrapolated from the values $U_{j}^{n}$ and $U_{j-1}^{n}$.
(b) $0 \leq \frac{\Delta x}{\Delta l} \leq c$


Schematic of the relationship between $\Delta x, \Delta t$ and $c$ leading to extrapolation of the solution at time-level $n+1$.

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Now defining $\Upsilon^{n}=\max _{j}\left|U_{j}^{n}\right|$, we have

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## Practical Exercise:

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Recall the story of Courant, Friedrichs and Lewy in Göttingen.

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Definition: $\left[u(j \Delta x, n \Delta t)-U_{j}^{n}\right]$ is the global truncation error.

Example: We use the criterion of the maximum method to study the stability condition of the diffusion equation

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A FDE approximation (FTCS scheme) is given by

$$
\frac{U_{j}^{n+1}-U_{j}^{n}}{\Delta t}=\sigma \frac{U_{j+1}^{n}-2 U_{j}^{n}+U_{j-1}^{n}}{\Delta x^{2}}
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We can write the FDE in the form

$$
U_{j}^{n+1}=\mu U_{j+1}^{n}+(1-2 \mu) U_{j}^{n}+\mu U_{j-1}^{n}
$$

where $\mu=\sigma \Delta t / \Delta x^{2}$.

Again,

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If we take absolute values, and let $\Upsilon^{n}=\max _{j}\left|U_{j}^{n}\right|$, we get

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Thus, we obtain the condition

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to insure that the solution remains bounded as $n \rightarrow \infty$. This is the necessary condition for stability of the FDE.

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We need a more powerful method of establishing stability.

## The von Neumann Method

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The space variable $x$ and the wavenumber $k$ can be multi-dimensional, e.g., $\mathbf{x}=\left(x_{1}, x_{2}, x_{3}\right), \mathbf{k}=\left(k_{1}, k_{2}, k_{3}\right)$ but, for simplicity, we will consider the scalar case.

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We define the wavenumber for the Fourier series: $p=k \Delta x$.
Then the Fourier expansion is

$$
U_{j}^{n}=\sum_{p} Z_{p}^{n} e^{i p j} \quad(\text { Note: } k x=k j \Delta x=p j)
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When we substitute this Fourier expansion into a linear FDE, we obtain a system of equations

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So, we must have $\left|\rho_{p}\right|^{n}<M$ for all $p$ as $n \rightarrow \infty$.

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We found that, for stability, we must have $|\rho|^{n}<M$ for all $p$ as $n \rightarrow \infty$. Clearly, this requires

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This is the von Neumann necessary condition for computational stability.

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For more complicated equations, the von Neumann criterion involves a matrix G rather than the amplification factor $\rho$.
The stability criterion then involves the eigenvalues of the amplification matrix, and the von Neumann stability criterion is $\|\mathbf{G}\| \leq 1+O(\Delta t)$.

## Application to Advection Equation

PDE: $\frac{\partial u}{\partial t}+c \frac{\partial u}{\partial x}=0$
FDE: $\frac{U_{j}^{n+1}-U_{j}^{n}}{\Delta t}+c \frac{U_{j}^{n}-U_{j-1}^{n}}{\Delta x}=0 \quad$ (upstream scheme)

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Since the equation is linear we can consider a single term

$$
U_{j}^{n}=A_{p} \rho_{p}^{n} e^{i p j}=A \rho^{n} e^{i p j}
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We substitute $U_{j}^{n}=A \rho^{n} e^{i p j}$ in the equation and divide by $U_{j}^{n}$ to obtain

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\frac{\rho-1}{\Delta t}+c \frac{\left(1-e^{-i p}\right)}{\Delta x}=0 \quad \text { for all } p
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We need to estimate the maximum value of $\rho$.

$$
\rho=1-\mu\left(1-e^{-i p}\right)=1-\mu(1-\cos p+i \sin p)
$$

Then the modulus squared is just

$$
|\rho|^{2}=[1-\mu(1-\cos p)]^{2}+\mu^{2} \sin ^{2} p
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To repeat,

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We make use of the trigonometrical relationships

$$
\cos p=\cos ^{2} \frac{p}{2}-\sin ^{2} \frac{p}{2}=c^{2}-s^{2} \quad \sin p=2 \sin \frac{p}{2} \cos \frac{p}{2}=2 s c
$$

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It is also consistent with the idea that we should not extrapolate but always interpolate to get the new values.

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An alternative, less damping scheme known as the Matsuno or Euler-backward scheme is also shown.


Amplification factor for the upstream scheme and the Matsuno scheme, with Courant Number $\mu=0.5$. Response for 1 step and 100 steps shown. $L$ is the wavelength in units of $\Delta x$.

